

BEHAVIORAL ASSUMPTION-BASED PREDICTION FOR HIGH-LATENCY HIDING IN MOBILE GAMES

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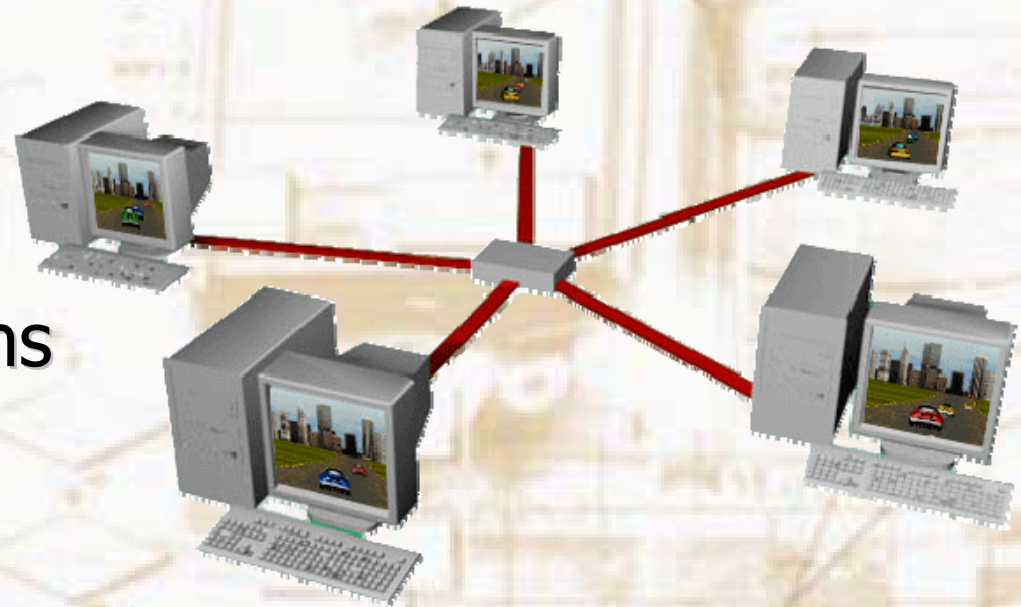
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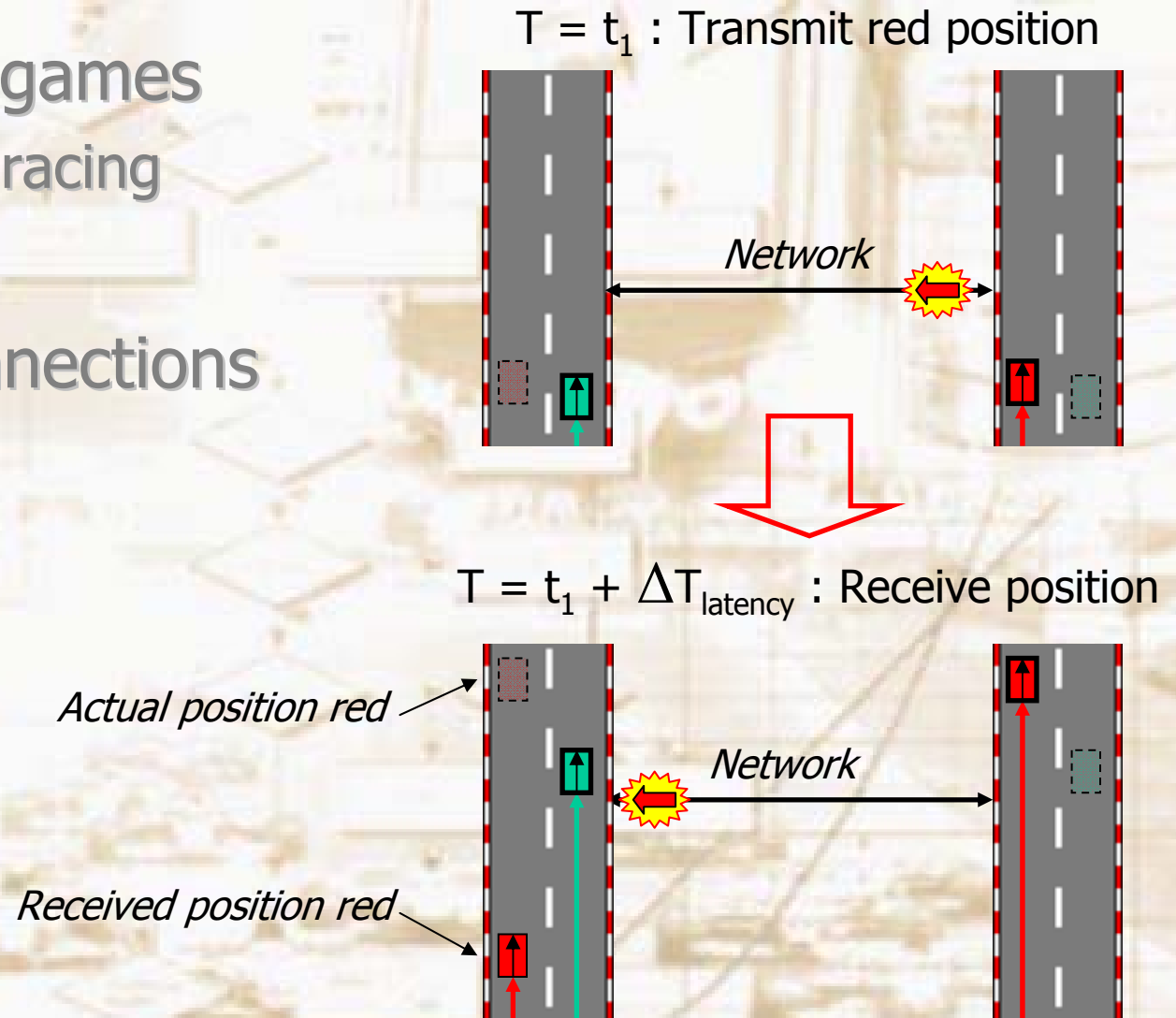
The problem

- Multi-player games
 - Fast-paced racing
- Network connections
- Latency



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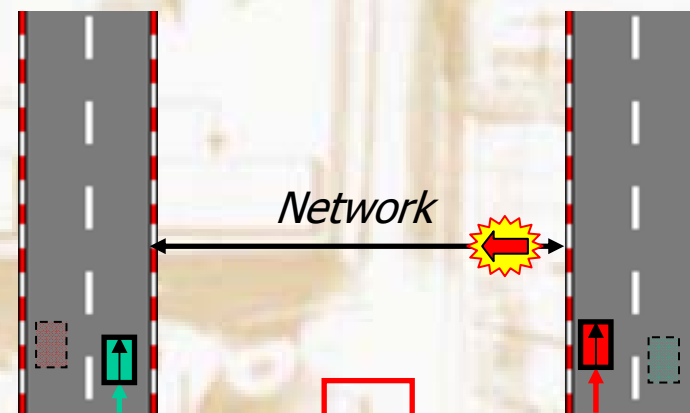
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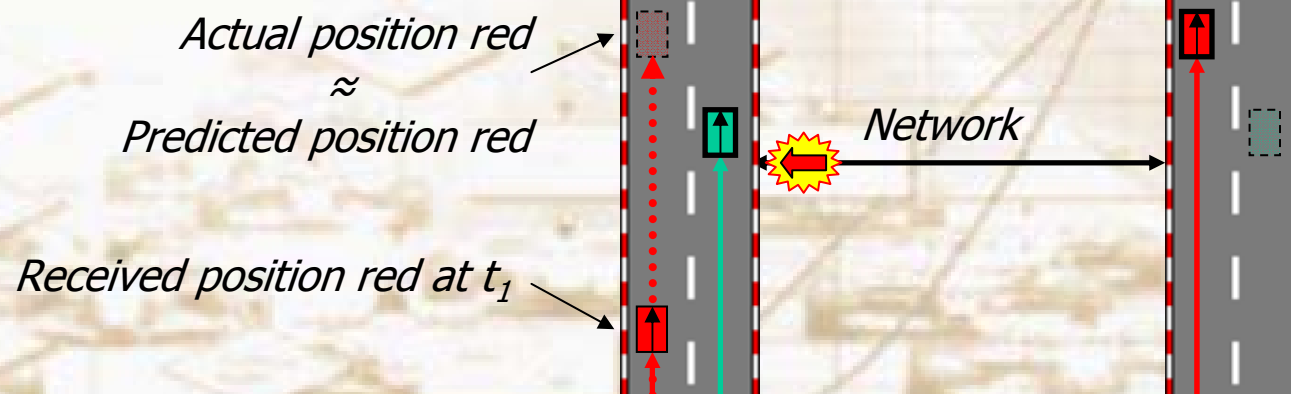
A common technique

- Prediction
- Prediction errors
- Dead reckoning

$T = t_1$: Transmit red position



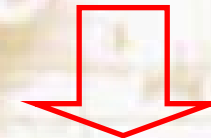
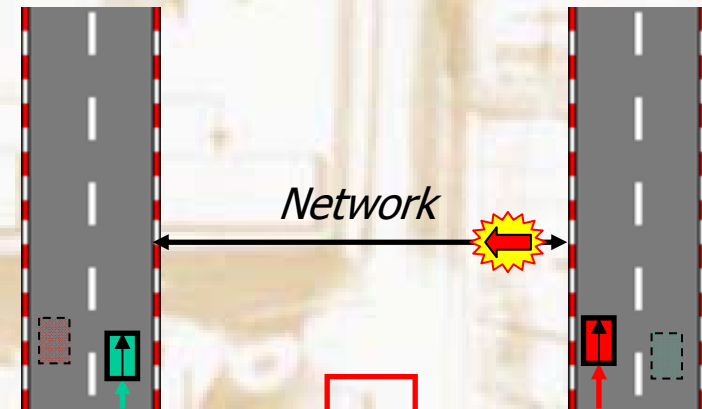
$T = t_1 + \Delta T_{\text{latency}}$: Receive position



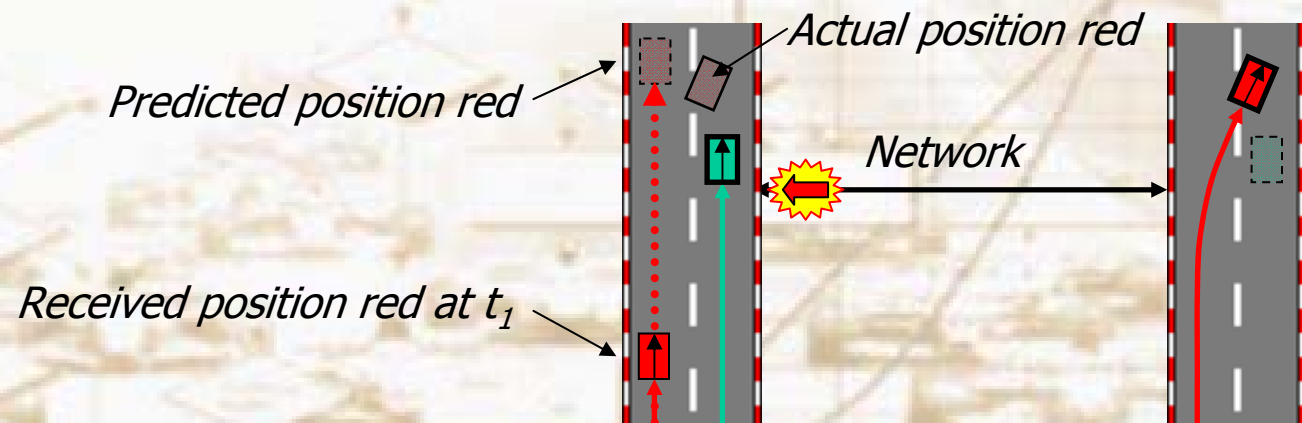
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Mobile games

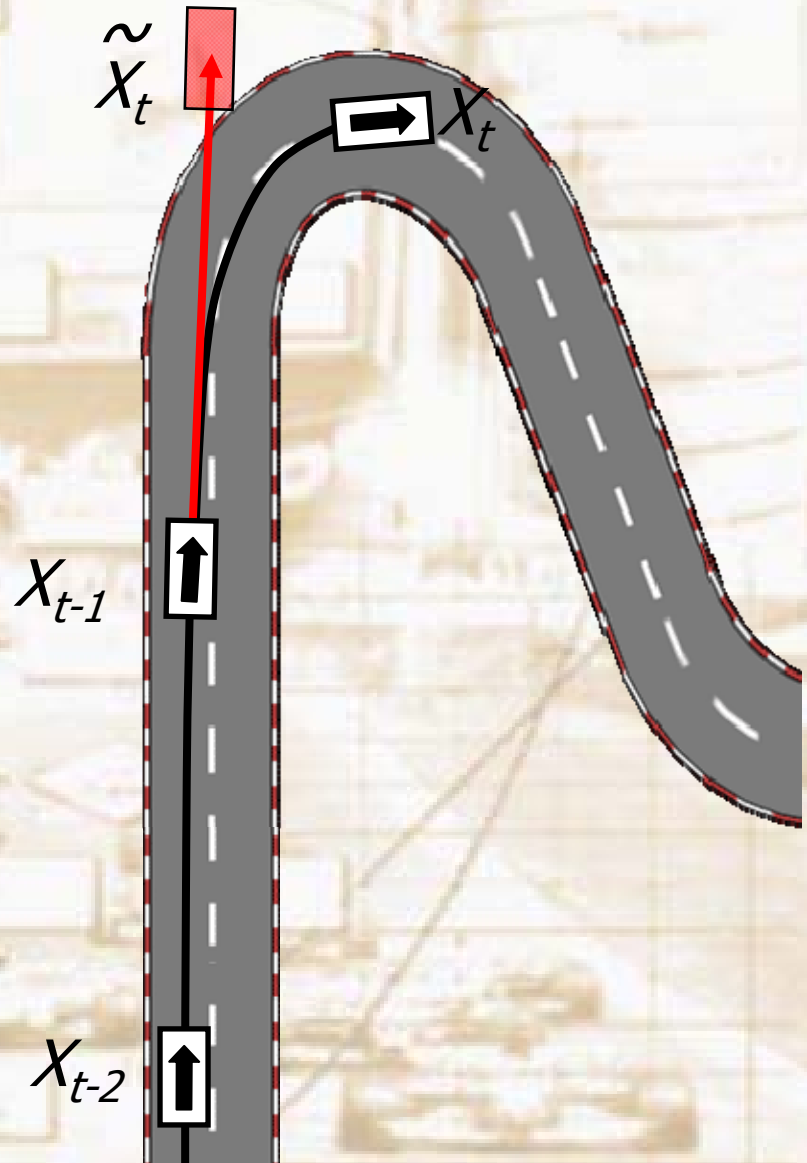
- Platform: Java, BREW, Symbian, ...
- Network: GPRS using HTTP/TCP/IP stack



	LAN network (PC game)	Internet (PC game)	GPRS network (Mobile game)
Network latency	1 - 5 ms	50 - 200 ms	1500 - 3500 ms
Prediction distance in a race game @ 100 km/h	0.03 – 0.14 meter	1.4 - 5.6 meter	42 – 97 meter
Prediction error, assuming a max. of 10% deviation.	< 2 cm	< 0.6 meter	< 10 meter
Results Dead- reckoning	Good.	Medium. Interactions like collisions can be problematic.	Bad. Errors as large as the width of a track are unacceptable.

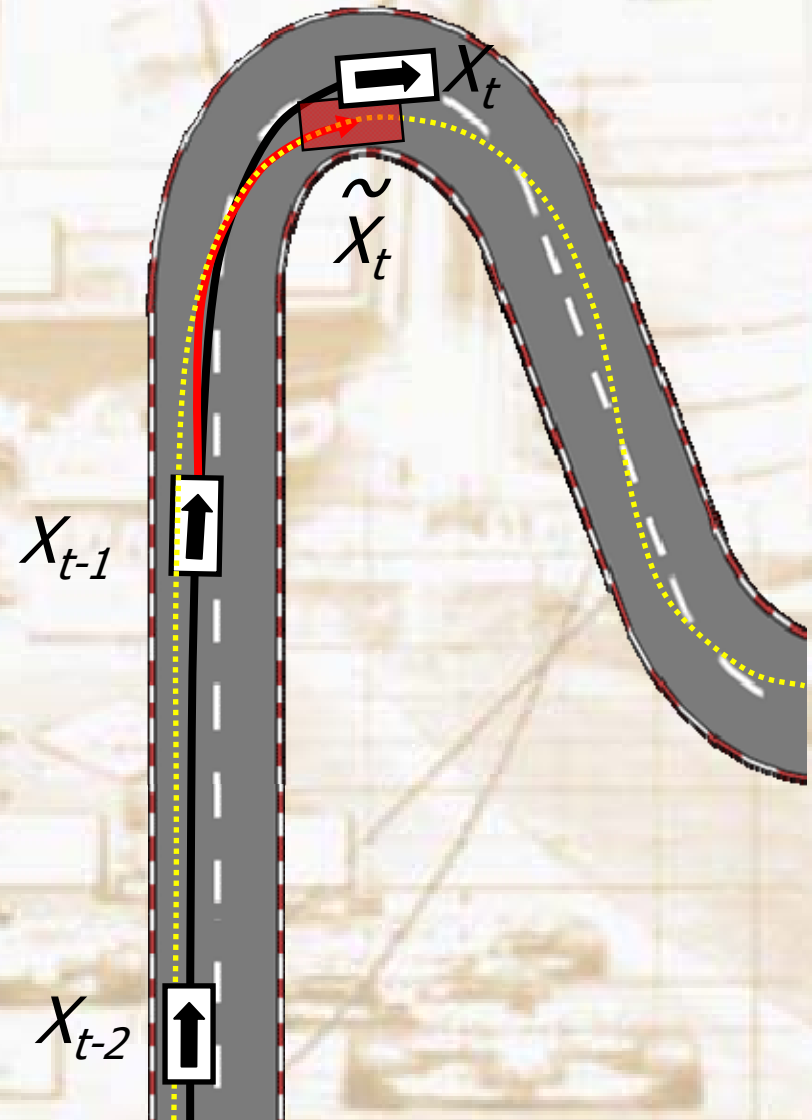
Prediction models

- Standard strategy:
 - Only extrapolate from older data
- Our approach:
 - Assume track following behavior
 - Or assume racing line optimizing behavior



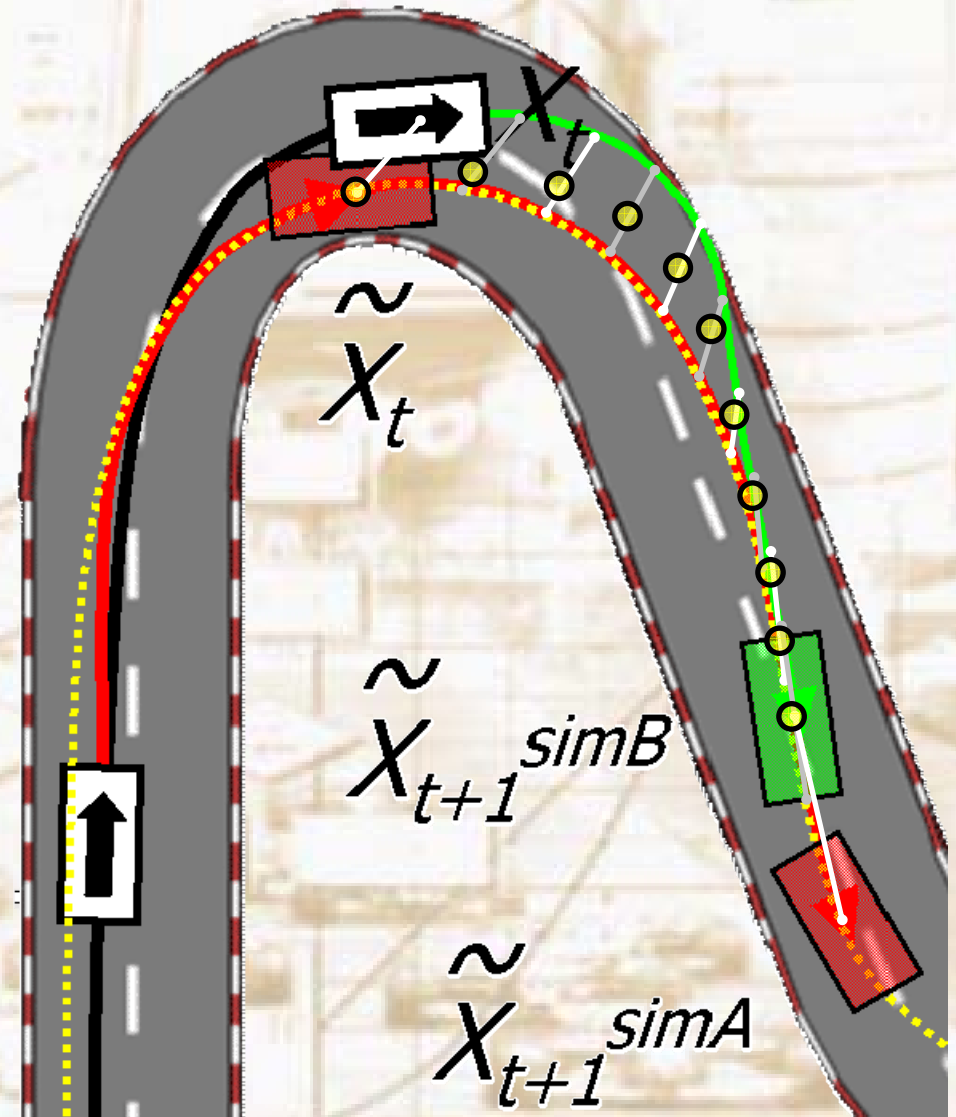
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Continuity

- Multiple simulations
 - Running 2 or 3 real-time simulations
 - Linear interpolation between simulations
 - Round robin



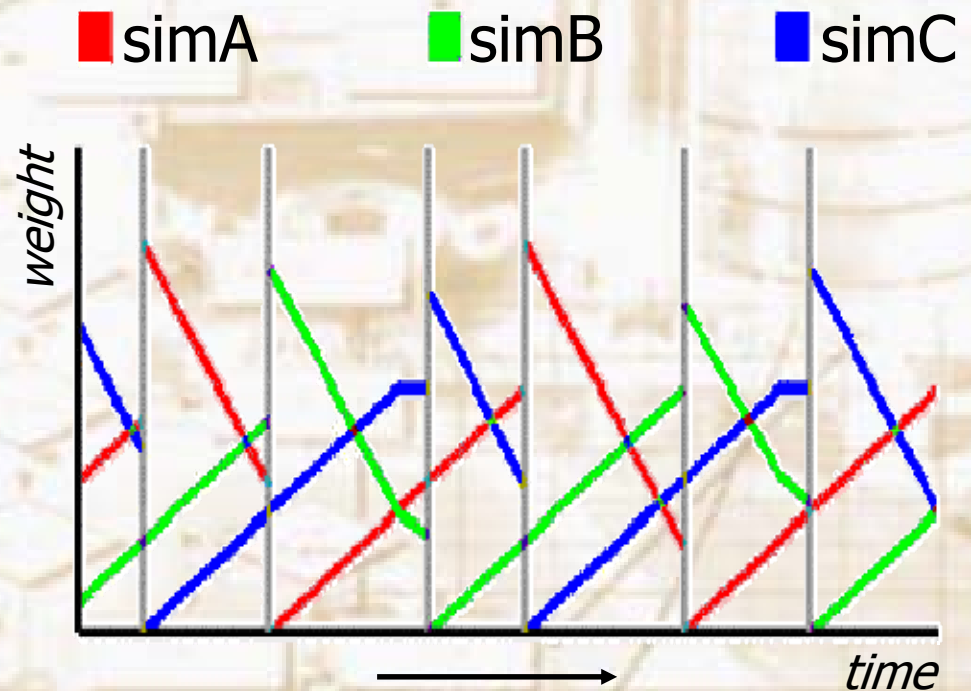
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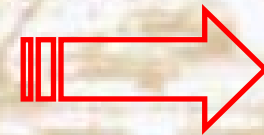
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A Test Drive

- Creating a testbed
- Comparing results
- Razor



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<http://www.exmachina.nl>

Conclusions

- Mobile 2.5G networks: a problematic domain
- Standard dead reckoning is insufficient
- Behavioral assumptions improve prediction
- Running multiple simulations: a good fit